### Estimating regulatory distortions of natural gas pipeline investment incentives

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#### Introduction

Interstate natural gas pipelines in US

- Regulated price of transmission set by rate-of-return
- Investment must be approved by regulator (FERC)
- How do the investment incentives faced by pipelines compare to the marginal value of investment?
- Estimate pipelines' perceived marginal value of investment from Euler equations
- Use differences in prices between trading hubs on pipeline network to measure marginal social value of investment

#### Natural gas is large and growing



#### Suggestive evidence of over-investment

- Rate-of-return regulation Averch-Johnson effect
  - Pipeline owners can raise their prices by increasing capital costs
- Rate of return allowed by FERC is high
  - von Hirschhausen (2008) : regulated rates of return average 11.6% for projects between 1996 and 2003
- FERC approves nearly all pipeline expansion projects only two rejected application between 1996 and 2016
- Some empirical evidence supporting overcapitalization (Oliver, Mason, and Finnoff, 2014; Hausman and Muehlenbachs, 2019)

### Suggestive evidence of under-investment

- Prices of natural gas at different locations sometime diverge
  - Cuddington and Wang (2006), Marmer, Shapiro, and MacAvoy (2007), Brown and Yücel (2008), Park, Mjelde, and Bessler (2008)
- Gas marketers, not pipeline owners, earn profits from arbitrage

#### Daily natural gas prices



#### Contributions

- Construct a detailed pipeline dataset from FERC and EIA filings
- Estimate pipelines' investment costs (including regulatory costs) from Euler Equations
  - Nonparametrically identified
  - Simple to estimate
  - ► Key assumption : information set of pipeline is observed or estimable
- Examine relationship between investment cost and pipeline network bottlenecks
- Areas of pipeline congestion have:
  - Lower regulatory marginal investment cost
  - Lower expected marginal product of capital

## Natural gas from production to consumption

- 1. Production at well-head
- 2. Gas purchased at well-head by marketer
- 3. Marketer pays pipeline to transport gas
- 4. Gas sold to :
  - Other marketer at hub
  - Local distribution company
  - Power plant or large industrial user
- 5. Local distribution company delivers gas to industrial and residential consumers

## Contracts between pipelines and marketers

- Long term (average 9.1 years) contracts for firm transportation service
  - Guaranteed right to transport a specified volume of gas along a pipeline per day
  - Large reservation charge
    - $\star\,$  Set by FERC using rate of return to cover capital costs
  - Small additional charge per unit used
    - $\star\,$  Set by FERC to cover marginal operating cost
- Unused capacity sold as interruptible transportation service
  - Price  $\leq$  reservation + utilization price of FTS
  - Open access short term auctions through online bulletin boards

### Building or expanding a pipeline

- 1. Obtain binding agreements from gas marketers to purchase 5-10 year FTS contracts for 80+% of planned capacity
- 2. File application with FERC
- 3. Public hearings, environmental assesments, etc
- 4. FERC approves 99% of applications
- ► Takes 1-3 years for new pipelines, much less for smaller projects
- Decommissioning and sales also need to be approved
- Streamlined for small projects
  - ► Automatic (<\$11,400,000) notify landowners 45 days in advance
  - Prior notice (<\$32,400,000) file plan with FERC, automatically approved after 60 days if no objection

## Pipeline network has failed to integrate regional markets



## Northeast is the primary physical bottleneck



#### Investment model

- Pipeline j choosing investment at time t
- Bellman equation:

$$V(k_t, s_t) = \max_{i_t} \frac{\pi(k_t, s_t) - c(i_t, k_t, s_t)}{R(i_t, k_t, s_t) \leq 0} + \beta E[V(k_t + i_t, s_{t+1}) | s_t, k_t + i_t]$$
Expectation over future state, given current state and capital regulatory constraint

Gross operating profit

- $i_{jt}$  = dollars of investment
- $s_{jt}$  = vector of observed and unobserved variables affecting profits, e.g.
  - $k_{-jt}$ , details of pipeline network, gas prices
- $\beta = \text{discount factor}$

#### Investment model: Euler Equation

#### Euler equation:

$$\frac{\partial c}{\partial i}(i_t, k_t, s_t) + \lambda_t \frac{\partial R}{\partial i}(i_t, k_t, s_t) = \beta \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c}{\partial i}(i_{t+1}, k_{t+1}, s_{t+1}) + \\ +\lambda_{t+1}\frac{\partial R}{\partial i}(i_{t+1}, k_{t+1}, s_{t+1}) + \\ -\frac{\partial c}{\partial k}(i_{t+1}, k_{t+1}, s_{t+1}) - \lambda_{t+1}\frac{\partial R}{\partial k}(i_{t+1}, k_{t+1}, s_{t+1}) \end{bmatrix}$$

• Define  $c_r(i, k, s) \equiv c(i, k, s) + \lambda R(i, k, s)$ 

$$\frac{\partial c_r}{\partial i}(i_t, k_t, s_t) = \beta \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial i}(i_{t+1}, k_{t+1}, s_{t+1}) + \\ -\frac{\partial c_r}{\partial k}(i_{t+1}, k_{t+1}, s_{t+1}) \end{bmatrix} \cdot \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial c_r}{\partial k}(i_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) + \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) \end{bmatrix} \mathbf{E} \begin{bmatrix} \frac{\partial \pi}{\partial k}(k_{t+1}$$

### Identification of $\frac{\partial c_r}{\partial i}$

#### ▶ $s_t, k_{t+1}$ observed, so $E[\cdot|k_{it+1}, s_t]$ is identified

 Substantitive assumption: econometrician observes all information used by firms to form expectations

• Observe 
$$\pi_{jt} = \pi(k_{jt}, x_{jt}) + \epsilon_{jt}$$
 so

$$\mathbf{E}[\pi_{jt}|k_{jt},x_{jt}]=\pi(k_{jt},x_{jt})$$

Only remaining unknown in Euler equation is marginal cost

### Pipeline data

▶ FERC Form 2/2a annual data on pipeline companies

- 1996-2019
- 96-123 companies each year
- detailed information about evenue, expenses, capital, transmission volume, etc
- Iimited information about pipeline locations and connections
- EIA form 176 has information on each pipelines' mileage and flow within each state and capacities between states
  - 1997-2019
  - merged with FERC data by company name 3% of pipeline mileage unmatched

#### Evolution of capital



### Distribution of investment













#### Estimation from Euler equation

First order condition and envelope theorem, and the boundary condition, give the Euler equation:

$$\frac{\partial c}{\partial i}(i_t, k_t, s_t) - \beta \mathbf{E} \left[ \frac{\partial c}{\partial i}(i_{t+1}, k_{t+1}, s_{t+1}) | s_t, k_{t+1} \right] = \beta \mathbf{E} \left[ \frac{\partial \pi}{\partial k}(k_{t+1}, s_{t+1}) | s_t, k_{t+1} \right]$$

- Estimation procedure:
  - 1. Estimate  $E[\frac{\partial}{\partial k}\pi_{t+1}|k_{t+1}, s_t]$  using an average derivative estimator based on Auto-DML details

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#### Estimation procedure:

- 1. Estimate  $E[\frac{\partial}{\partial k}\pi_{t+1}|k_{t+1}, s_t]$  using an average derivative estimator based on Auto-DML details
- 2. Estimate  $E\left[\cdot | s_t, k_{t+1}\right]$  with a Reproducing Kernel Hilbert Space (RKHS) embedding
- 3. Invert the conditional expectation onto the profit function to



#### Auto-DML problem statement

- ► The problem of predicting future profits is very high dimensional
- Modern machine learning methods are really good at this type of prediction. Deep learning in particular for dynamic economic problems (Kahou et al. 2025). Especially when paired with regularization.
- Regularization creates bias in the estimator. It fits the profit function better, but would bias our estimates of the derivative θ<sub>0</sub> = E[∂/∂k π<sub>t+1</sub>|k<sub>t+1</sub>, s<sub>t</sub>].
- Goal, estimate θ<sub>0</sub> in such a way that it is robust to small perturbations of the nuisance parameters (ζ) of the ML estimator

• Neyman orthogonality: 
$$\partial_{\zeta} E \left[ \frac{\partial}{\partial k} \hat{\pi}_{t+1}^{\zeta} | k_{t+1}, s_t \right] \Big|_{\zeta} = 0$$



Figure: Graphical description of the Auto-DML architecture used to recover and debias the profit function.

back to slides

Pipeline investment

#### • Goal is to estimate $\theta_0 = \operatorname{E}[m(k_{t+1}, s_t; \pi(\cdot), k_{t+1}, s_t)] = \operatorname{E}[\frac{\partial}{\partial k} \pi_{t+1} | k_{t+1}, s_t]$

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- First stage: estimate π̂ = arg min<sub>π</sub> E[(π<sub>t+1</sub> − π<sub>0</sub>)<sup>2</sup> | k<sub>t+1</sub>, s<sub>t</sub>] using deep neural net

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- ► Use a hidden layer of the deep network as inputs to another deep network to estimate  $\hat{\alpha} = \arg \min_{\alpha} E[(\alpha \alpha_0)^2 | k_{t+1}, s_t]$ 
  - $\alpha_0$  is the Riesz representer of the moment function. Exists by linearity of m
  - e.g. a function such that  $E[m(k_{t+1}, s_t, \pi_{t+1}; g(\cdot)) \mid k_{t+1}, s_t] = E[\alpha_0(k_{t+1}, s_t)g(k_{t+1}, s_t) \mid k_{t+1}, s_t]$
  - ▶ substitute the above into the loss function for  $\hat{\alpha}$ , gives  $\hat{\alpha} = \arg \min_{\alpha} \mathbb{E}[\alpha(X)^2 2m(W, \alpha)]$ , new objective does not depend on  $\alpha_0$ .
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27 / 45

#### Estimation of regulatory cost

- Suppose that  $\frac{\partial c_r}{\partial i} \in \mathcal{H}$ , a reproducing kernel Hilbert space
  - with kernel  $k: S \times S \rightarrow \mathbb{R}$
  - inner product  $\langle \cdot, \cdot \rangle$
  - elements of  $\mathcal H$  are functions from state space S to  $\mathbb R$
  - $\flat \langle f, k(s, \cdot) \rangle = f(s)$
- Goal is to estimate a Riesz representer  $\mu(x, \cdot)$  such that  $E[f(s') | s = x] = \langle f, \mu(x, \cdot) \rangle$
- Note that

$$\begin{split} & \operatorname{E}\left[\left(f(s') - \langle f, \mu(s, \cdot) \rangle\right)^2\right] = \operatorname{E}\left[\langle f, k(s', \cdot) - \mu(s, \cdot) \rangle^2\right] \\ & \leq \|f\|^2 \operatorname{E}[\|k(s', \cdot) - \mu(s, \cdot)\|^2]. \end{split}$$

Estimate µ by solving

$$\min_{\mu} \frac{1}{N(T-1)} \sum_{i=1}^{N} \sum_{t=1}^{T-1} \|k(s_{it+1}, \cdot) - \mu(s_{it}, \cdot)\|^2 + \lambda \|\mu^2\|$$

#### Estimation of regulatory cost

The minimizer is

$$\hat{\mu}(s,s') = k(s,\mathbf{s}_t) (K + \lambda I)^{-1} k(\mathbf{s}_{t+1},s')$$

- K is an  $N(T-1) \times N(T-1)$  matrix with entries  $k(s_{it}, s_{jr})$
- $k(s, \mathbf{s}_{t+1})$  is a  $1 \times N(T-1)$  vector with elements  $k(s, s_{it+1})$
- ▶  $k(\mathbf{s}_t, s')$  is a  $N(T-1) \times 1$  vector with elements  $k(s_{it}, s')$ .

• With this  $\hat{\mu}$ , the estimate of the conditional expectation is then

$$\begin{split} \mathbf{E}[\widehat{f(s')}|s] &= \langle f, \hat{\mu}(s, \cdot) \rangle \\ &= k(s, \mathbf{s}_t) \left( K + \lambda I \right)^{-1} f(\mathbf{s}_{t+1}). \end{split}$$

- Standardize each component of s to have zero mean and unit variance
- Gaussian kernel,  $k(s, s') = e^{-\|s-s'\|^2}$ , and set  $\lambda = 1$ .

▶ Represent  $\frac{\partial c_r}{\partial i}$  by a neural network, minimize Euler residuals

$$\min_{\frac{\partial c_{T}}{\partial i}} \frac{1}{N(T-1)} \sum_{i,t}^{N,T-1} \left( \frac{\partial c_{r}}{\partial i}(s_{it}) - \beta k(s_{it},s_{t}) \left(K + \lambda I\right)^{-1} \frac{\partial c}{\partial i}(s_{t+1}) - \mathrm{E}\left[ \widehat{\frac{\partial \pi}{\partial k}(k_{t+1},s_{t+1})} \middle| s_{t},k_{t+1} \right] \right)^{2}.$$

Pipeline investmen

### Marginal product of capital hovers around previous estimates



#### Northeast has the highest regulatory costs



Figure: Investment projects in the Northeast are profitable, so investment distortion is driven primarily by increased regulatory costs.

#### Unbalanced distribution of costs



Figure: Investment costs in the northeast are lowest for investments that are likely to be the most profitable.

#### Prices and social value

How do these estimated regulatory costs compare to the optimal regulation?

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- How do these estimated regulatory costs compare to the optimal regulation?
- To find out, make a further assumption that there is a continuum of marketers (marketers are perfectly competitive).
- Under this assumption, prices arise from the optimal dispatch problem with a flow constraint (similar to the model used in Cremer, Gasmi and Laffont, 2003)

### Optimal dispatch



- A social planner wants to choose where to expand capacity constraints κ<sub>ij</sub>
- ► Key finding: The Lagrange multiplier on the capacity constraint is equal to the difference in prices across a state border details

Pipeline investment

Social Value of Pipeline Capacity

### Social planner invests to minimize price gaps

► Envelope theorem:  $\frac{\partial v}{\partial \kappa_{ij}} = \lambda_{ij} = \max \{ p_i - p_j - c_{ij}, 0 \}$ . Under the same boundary condition, Euler can be written as

$$\frac{\partial c}{\partial i}(i_t, k_t, s_t) - \beta \mathbf{E} \left[ \frac{\partial c}{\partial i}(i_{t+1}, k_{t+1}, s_{t+1}) \mid s_t, k_{t+1} \right] = \beta \sum_{m=1}^{12} \sum_{j=1}^n \sum_{\ell=1}^n \mathbf{E} \left[ \frac{\partial \kappa_{j\ell}}{\partial k} \max\{p_{jmt+1} - p_{\ell mt+1} - c_{j\ell}, 0\} \mid s_t, k_t \in \mathbb{C} \right]$$

- This is identical to the firm's Euler equation, except:
  - 1. The objective on the right hand side is marginal social value of capital, instead of marginal profit
  - 2. *c*, not *c*, on the left hand side. (*c* does not contain the extra regulatory cost)
- Right hand side can be estimated using a similar Auto-DML procedure.



Figure: Assuming that the regulator's Euler equation holds on average point-identifies the discount factor at 0.99

#### Measuring social value

 Subtract planner's Euler from firms' to obtain the PDE for optimal regulation

$$\begin{split} \beta & \mathbf{E} \left[ \lambda_{t+1} \frac{\partial \mathbf{R}^*}{\partial i} (i_{t+1}, k_{t+1}, \mathbf{s}_{t+1}) - \lambda_{t+1} \frac{\partial \mathbf{R}^*}{\partial k} (i_{t+1}, k_{t+1}, \mathbf{s}_{t+1}) \Big| \mathbf{s}_t, k_{t+1} \right] - \lambda_t \frac{\partial \mathbf{R}^*}{\partial i} (i_t, k_t, \mathbf{s}_t) = \\ \beta & \mathbf{E} \left[ \left( \sum_{r=1}^{12} \sum_{j=1}^n \sum_{\ell=1}^n \frac{\partial \kappa_{j\ell}}{\partial k} \max\{ p_j - p_\ell - c_{j\ell}, 0\} \right) - \frac{\partial \pi}{\partial k} (k_{t+1}, \mathbf{s}_{t+1}) \Big| \mathbf{s}_t, k_{t+1} \right]. \end{split}$$

- Note: If the right hand side is negative, capital is overincentivized and at least some additional regulation must be used to get optimal investment
- Denote the right hand side difference as Δ. Estimate using the same debiased method used to recover profits

## Negative delta indicates there is need for regulation



Figure: Delta is consistently negative – fixed rates universally exceed social value so some regulation is needed to realign incentives

Pipeline investment

Social Value of Pipeline Capacity

# Regulatory costs are too stringent in New England



Figure: In the northeast, firms are not incentivized to invest under the current regime; but there may be overinvestment in parts of the midcoast and mountain

# How well targeted is investment regulation?



Figure: Regulation costs have risen in the northeast and are decreasing in parts of the southern and mountain regions

- We set out to investigate whether the regulatory incentives for pipeline development are distorting the growth of the natural gas pipeline network.
- Develop a structural model to estimate firm investment incentives
  - Novel method uses deep networks and RKHS embeddings to estimate network investment incentives from firm Euler equations
  - Estimated on firm-level administrative data from FERC Form 2A and EIA Form 176

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- Develop a structural model to estimate firm investment incentives
  - Novel method uses deep networks and RKHS embeddings to estimate network investment incentives from firm Euler equations
  - Estimated on firm-level administrative data from FERC Form 2A and EIA Form 176
- Solve a benchmark model of optimal pipeline investment by a social planner
  - Social planner would place new capacity in areas with large price gaps, instead of those with potential profit
  - Regulator can realign incentives by limiting investment through a costly approval process

- Find that investment incentives of pipelines were not aligned with social value of investment over the time period from 1996-2019
  - Large investment overall but has not improved the bottleneck into New England

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  - Large investment overall but has not improved the bottleneck into New England
- Most of the variation in investment is driven by the costly approval process, as opposed to varying rates.
- Using our model, characterized the importance of costly investment approvals as a secondary control.
  - Over this time period, investment costs in New England were too high
  - In the lower east coast and parts of the mountain west, there is overinvestment relative to social value. Regulation could be tightened in these areas

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